# Learning to Explore Paths for Symbolic Execution

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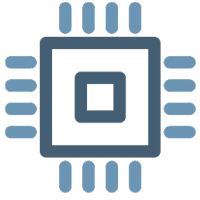
# Symbolic Execution

## A powerful technique widely adopted in security

Analyzing
Protocol
Implementations



Validating
Hardware
Design

Securing
Smart
Contracts

## Can be used to generate "good" tests

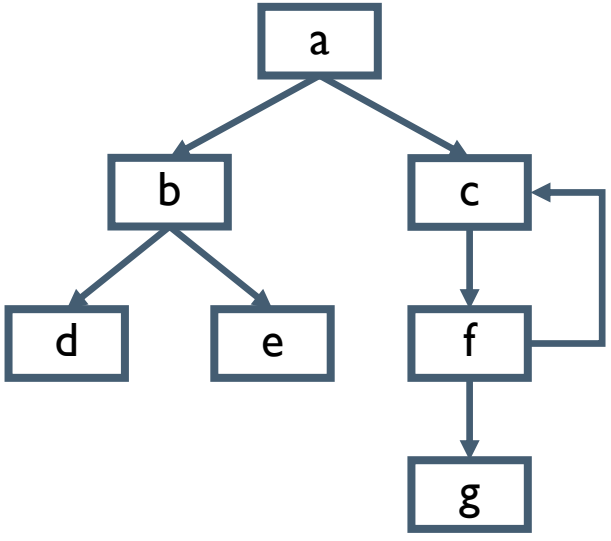
SAGE

Symbolic
PathFinder

Apollo

Icons made by Kiranshastry from www.flaticon.com

# Path Exploration and Explosion




**Candidate States:**

$a_0$ $b_0$ $c_0$ $d_0$ $e_0$

**Tests Generated:**

$a_0$-$b_0$-$e_0$

**Coverage Objective of Symbolic Execution:**

$$\arg\max_{tests} \frac{|\cup_{t \in tests} \text{coverage}(t)|}{totalTime}$$

**Path Explosion:**

**#states is exponential in #branches**

**#states explodes at deep branches**

**e.g., 10k-100k states for coreutils**

**Need a Good Strategy to Select Promising States!**

# State Selection Strategies

**State Selection Strategies:**
(can be deterministic or probabilistic)


**The Ideal State Selection Strategy?**

**Coverage Objective of Symbolic Execution:** $\arg\max_{tests} \frac{|\bigcup_{t \in tests} \text{coverage}(t)|}{totalTime}$

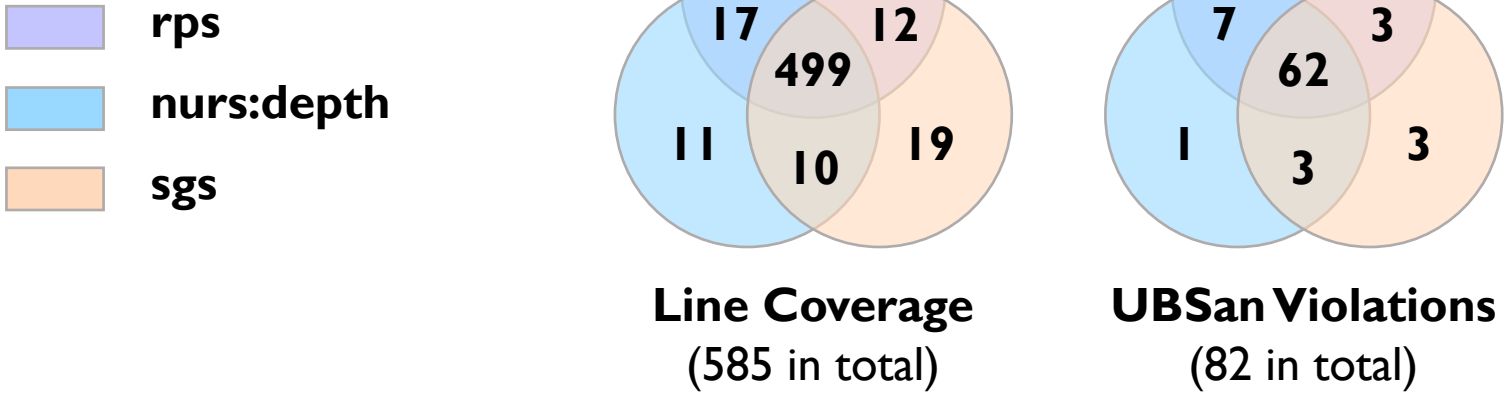
**Selection with an Ideal Reward Function:** $\text{reward}(s) = \frac{|\bigcup_{t \in \text{testsFrom}(s)} \text{coverage}(t)|}{\sum_{d \in \text{statesFrom}(s)} \text{stateTime}(d)}$

**Cannot Calculate testsFrom and statesFrom!**

# Existing State Selection Heuristics

**Existing Heuristics:** select states based on certain property of the states. Often get stuck in program parts favoring the property but fail to explore other parts

**Running KLEE on coreutils (1h)**

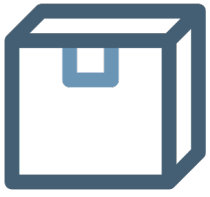



**Line Coverage**
(585 in total)

**UBSan Violations**
(82 in total)

**Expectation for Learning:** an adaptive strategy subsuming individual heuristics

# Learch: our Learned Strategy



**State**



**Feedforward Networks**



**Predicted Reward**

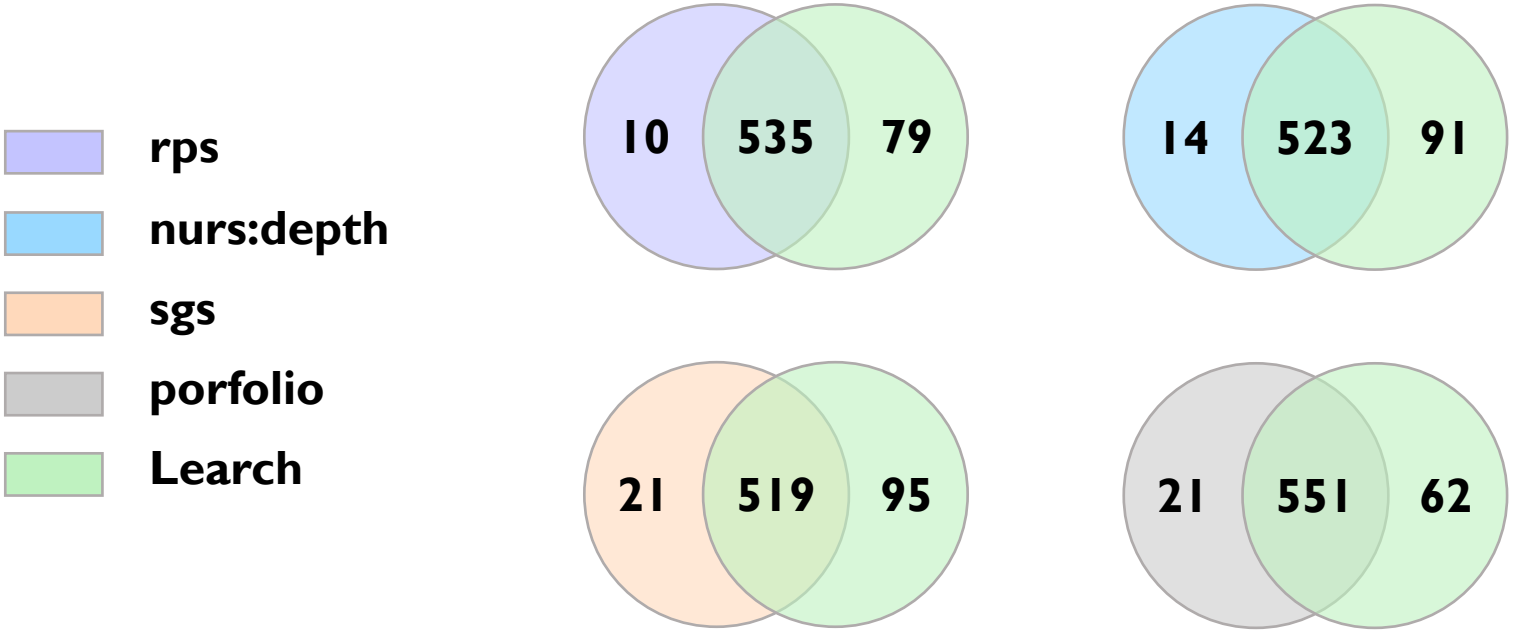
$$\frac{|\bigcup_{t \in \text{testsFrom}(s)} \text{coverage}(t)|}{\sum_{d \in \text{statesFrom}(s)} \text{stateTime}(d)}$$

**Training Dataset**

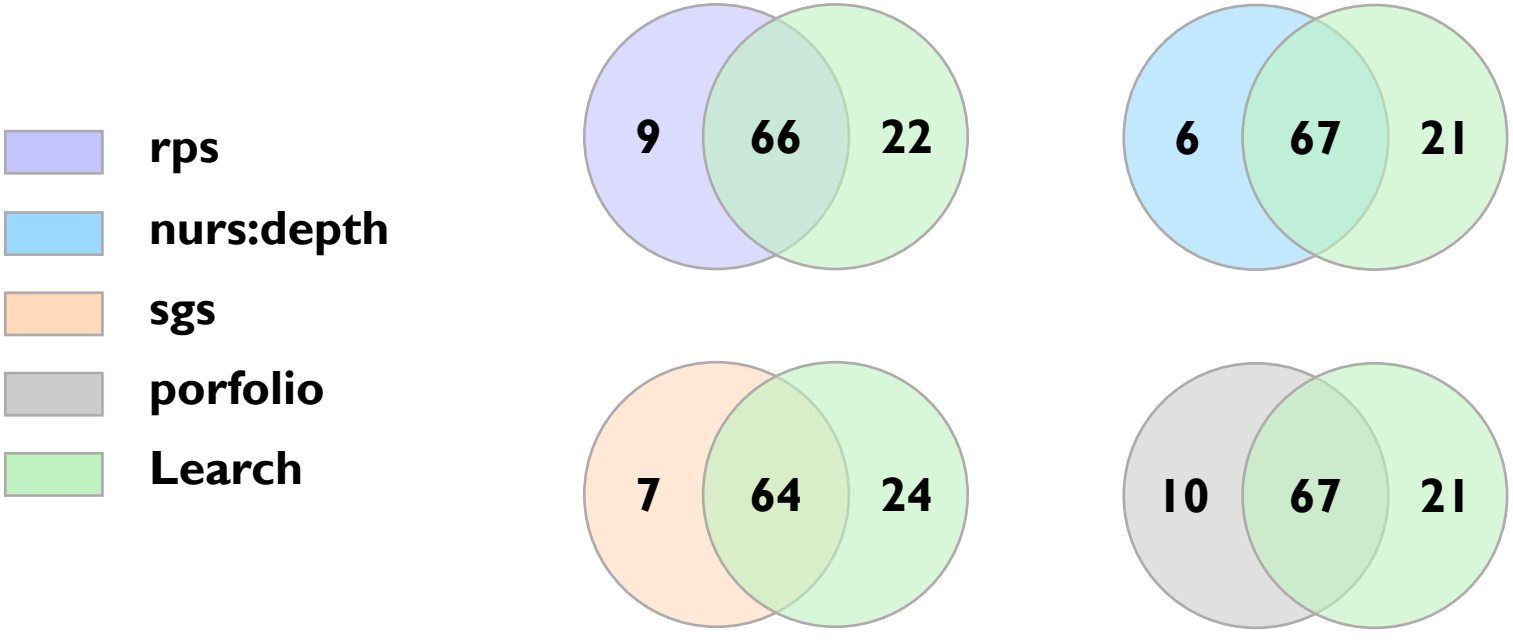
**Features**

**Manuel Heuristics**

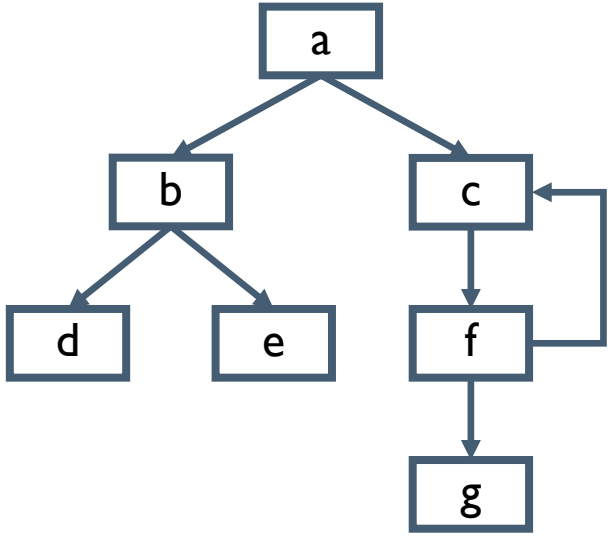
# Learch: Line Coverage on coreutils



# Learch: UBSan Violations on coreutils



# Obtaining a Supervised Dataset



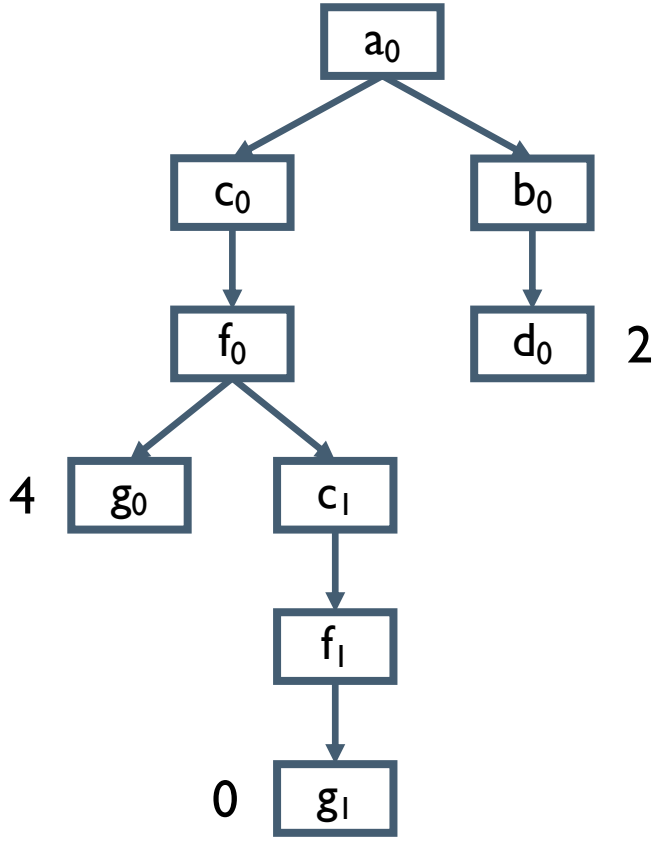

| | States | Cov | NewCov |
|---|---|---|---|
| 1 | $a_0$-$c_0$-$f_0$-$g_0$ | a, c, f, g | a, c, f, g |
| 2 | $a_0$-$c_0$-$f_0$-$c_1$-$f_1$-$g_1$ | a, c, f, g | ∅ |
| 3 | $a_0$-$b_0$-$d_0$ | a, b, d | b, d |

| $a_0$ | $c_0$ | $f_0$ | $g_0$ | $c_1$ | $f_1$ | $g_1$ | $b_0$ | $d_0$ |
|---|---|---|---|---|---|---|---|---|
| 1 | 2 | 2 | 2 | 1 | 1 | 2 | 2 | 2 |

**Time Spent by Each State**

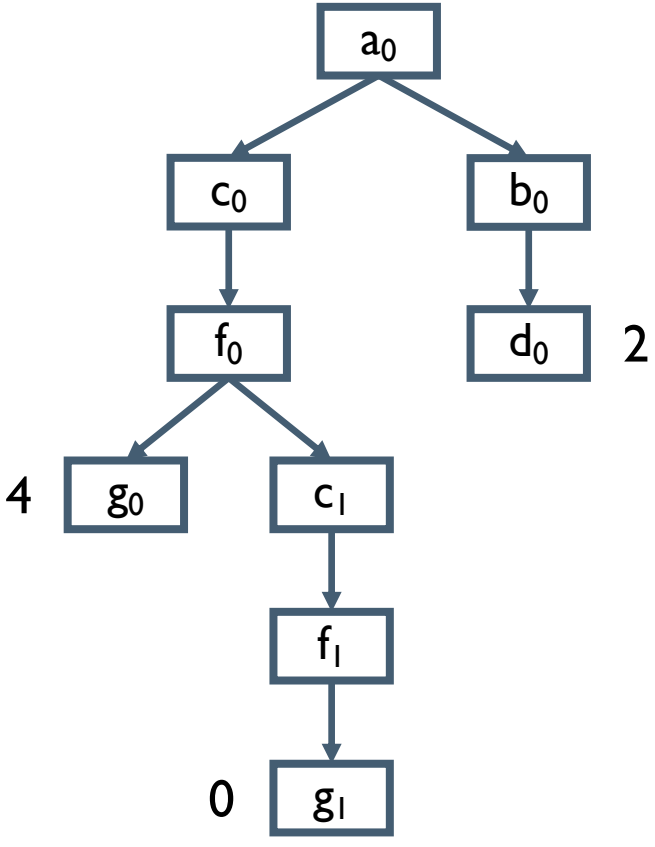
# Obtaining a Supervised Dataset

| | States | Cov | NewCov |
|---|---|---|---|
| 1 | $a_0$-$c_0$-$f_0$-$g_0$ | a, c, f, g | a, c, f, g |
| 2 | $a_0$-$c_0$-$f_0$-$c_1$-$f_1$-$g_1$ | a, c, f, g | ∅ |
| 3 | $a_0$-$b_0$-$d_0$ | a, b, d | b, d |




**Tests Tree**

# Obtaining a Supervised Dataset




| State | Time | TotalCov | TotalTime | Reward |
|---|---|---|---|---|
| $a_0$ | 1 | 6 | 15 | 0.4 |
| $c_0$ | 2 | 4 | 10 | 0.4 |
| $f_0$ | 2 | 4 | 8 | 0.5 |
| $g_0$ | 2 | 4 | 2 | 2 |
| $c_1$ | 1 | 0 | 4 | 0 |
| $f_1$ | 1 | 0 | 3 | 0 |
| $g_1$ | 2 | 0 | 2 | 0 |
| $b_0$ | 2 | 2 | 4 | 0.5 |
| $d_0$ | 2 | 2 | 2 | 1 |

# Obtaining a Supervised Dataset

**Procedure** genData

**Input:** a set of training programs 
a set of strategies 

**Output:** a supervised dataset 

 ← ∅

**For each**  **and** 

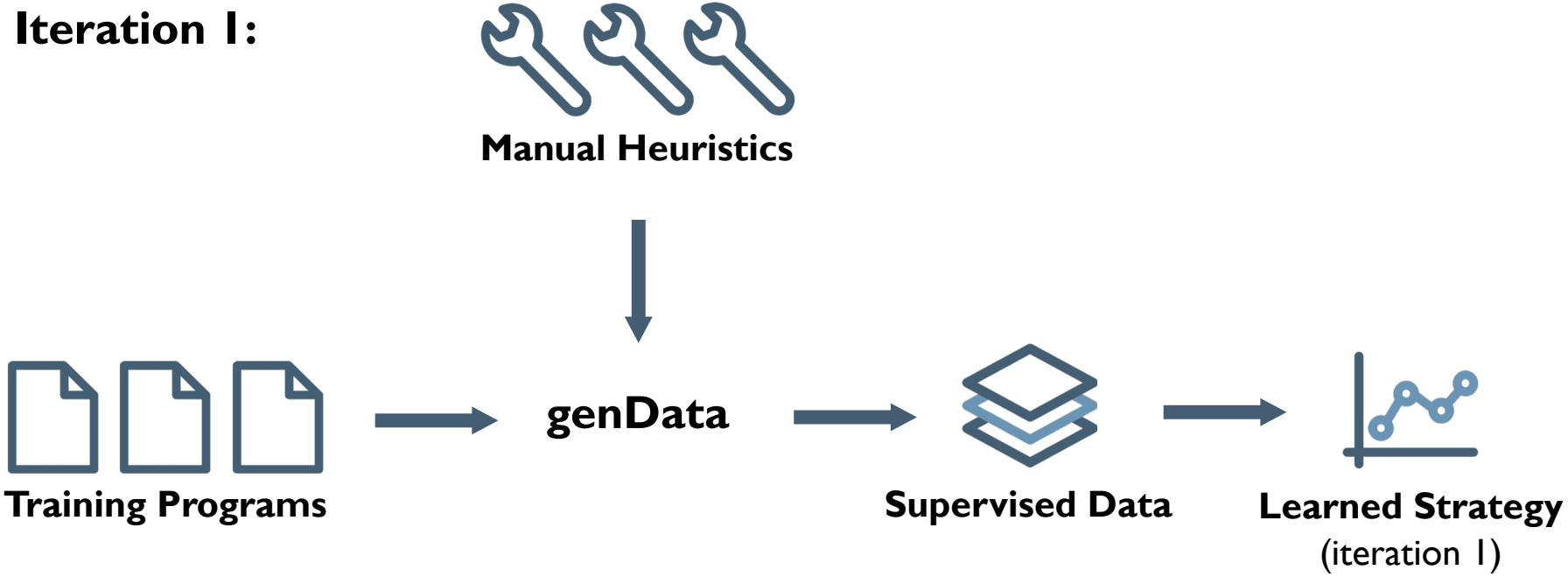
**Obtain new data**  **on**  **with** 

**Add**  **to** 

**Return** 

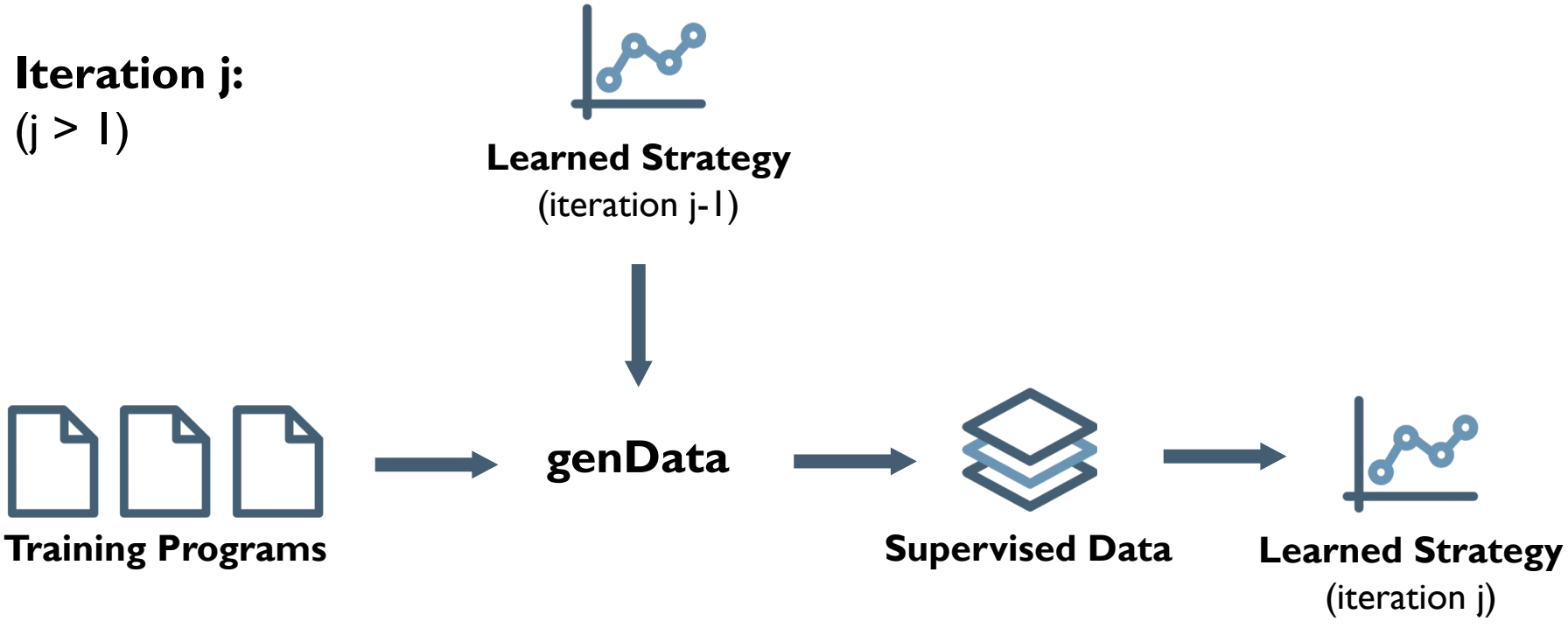
# Final Iterative Learning Algorithm

**Iteration 1:**



# Final Iterative Learning Algorithm

**Iteration j:**
(j > 1)



# Instantiation Learch on KLEE

**Features:** stack, successor, testCase, coverage, constraint, **depth**, **cpicnt**, **icnt**, **covNew**, **subpath**

**UBSan Violations:** Integer overflow, oversized shift, out-of-bound array reads/writes, pointer overflow, null deference

Run 4 learned strategies, each taking a quarter of the total time limit, and combine all generated tests

# Evaluation: Line Coverage (8h runs)

**diff**

portfolio 1136

Learch 1791

**grep**

portfolio 2003

Learch 2421

**gawk**

sgs 2885

Learch 3097

**patch**

sgs 1412

Learch 1502

**objcopy**

rss 2131

Learch 2827

**readelf**

portfolio 1192

Learch 1179

**make**

portfolio 2353

Learch 2398

**sqlite**

nurs:cpicnt 5204

Learch 5590

**find**

portfolio 3142

Learch 2927

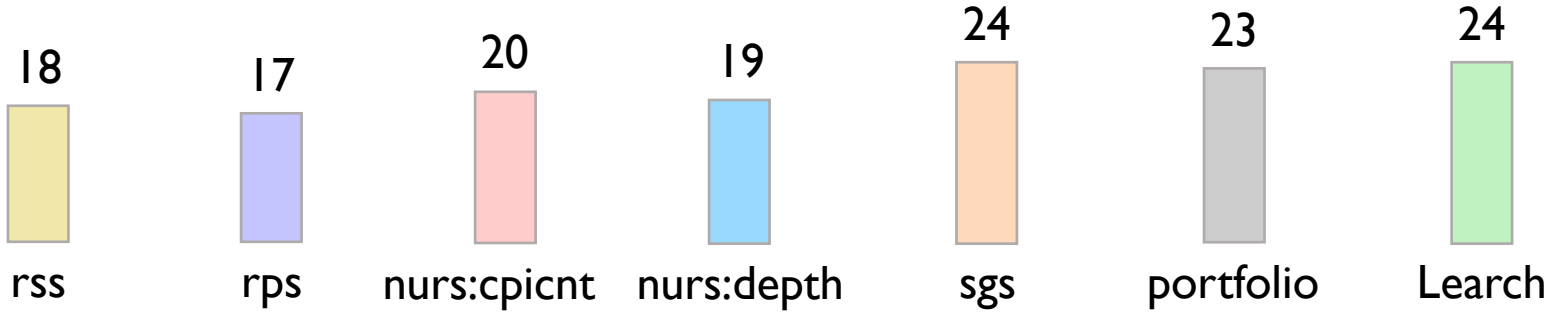
**cjson**

portfolio 551

Learch 541

**On Average, >20% increase than all heuristics**

# Evaluation: UBSan Violations (8h run)



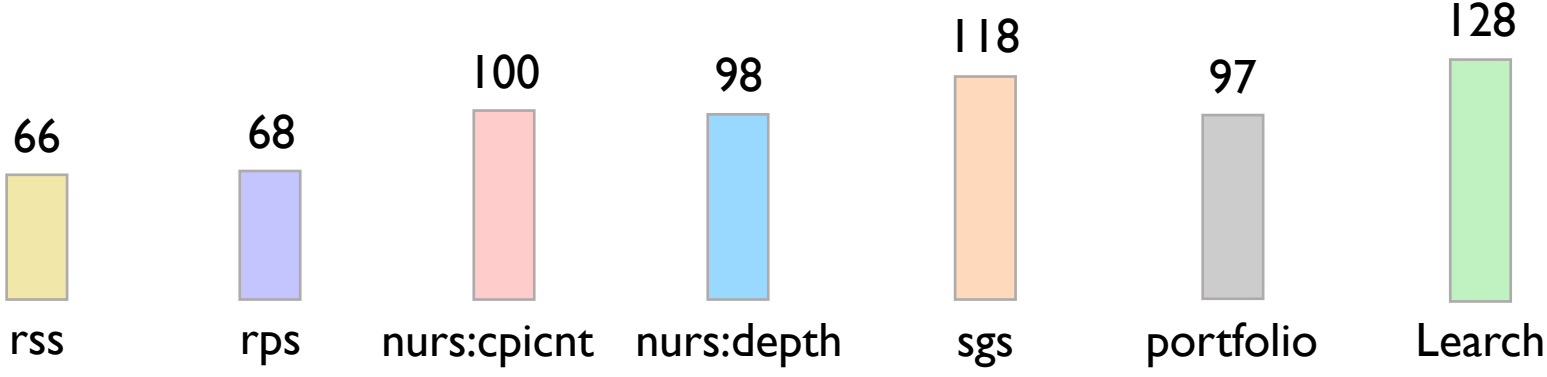

**46 reports to developers, 13 confirmed, 11 fixed**

# Evaluation: Seeding AFL (8h runs)

## Discovering Paths

| objcopy | | readelf | | make | | sqlite | |
|---|---|---|---|---|---|---|---|
| sgs | 2489 | nurs:depth | 4133 | rps | 5582 | sgs | 4243 |
| Learch | 2882 | Learch | 4531 | Learch | 5689 | Learch | 4364 |

## Detecting UBSan Violations



# Evaluation: Design Choices (1h runs)

**Line Coverage**

**566 566 560 563** 4 individual strategies

**618** Learch

**517** linear

**541** rnn

**618** Learch

**UBSan Violations**

**71 75 70 93** 4 individual strategies

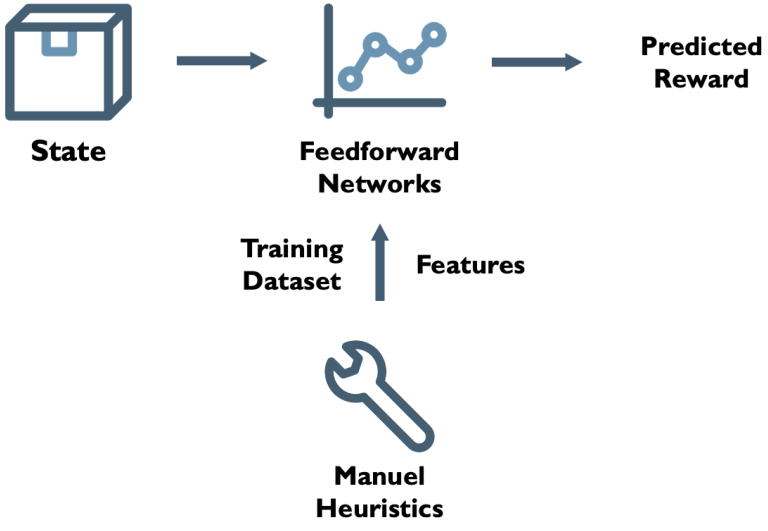
**88** Learch

**62** linear

**70** rnn

**88** Learch

# Summary

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