

# Learning Fast and Precise Numerical Analysis



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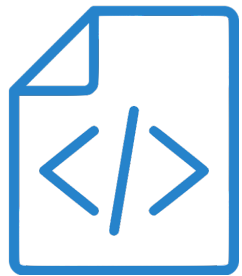


Martin Vechev

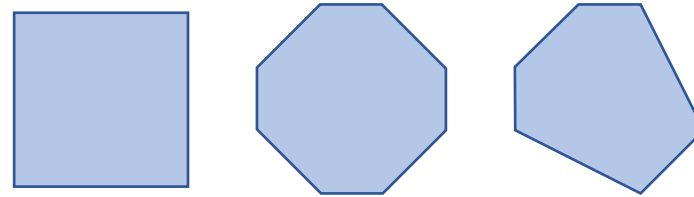
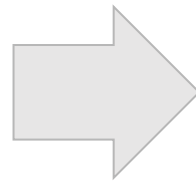
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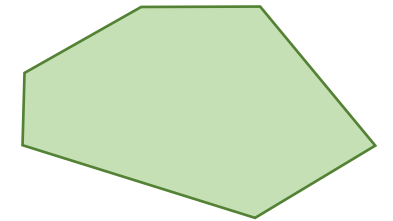
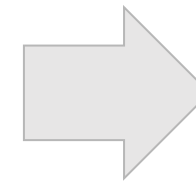
# Numerical program analysis



Program



Abstract elements

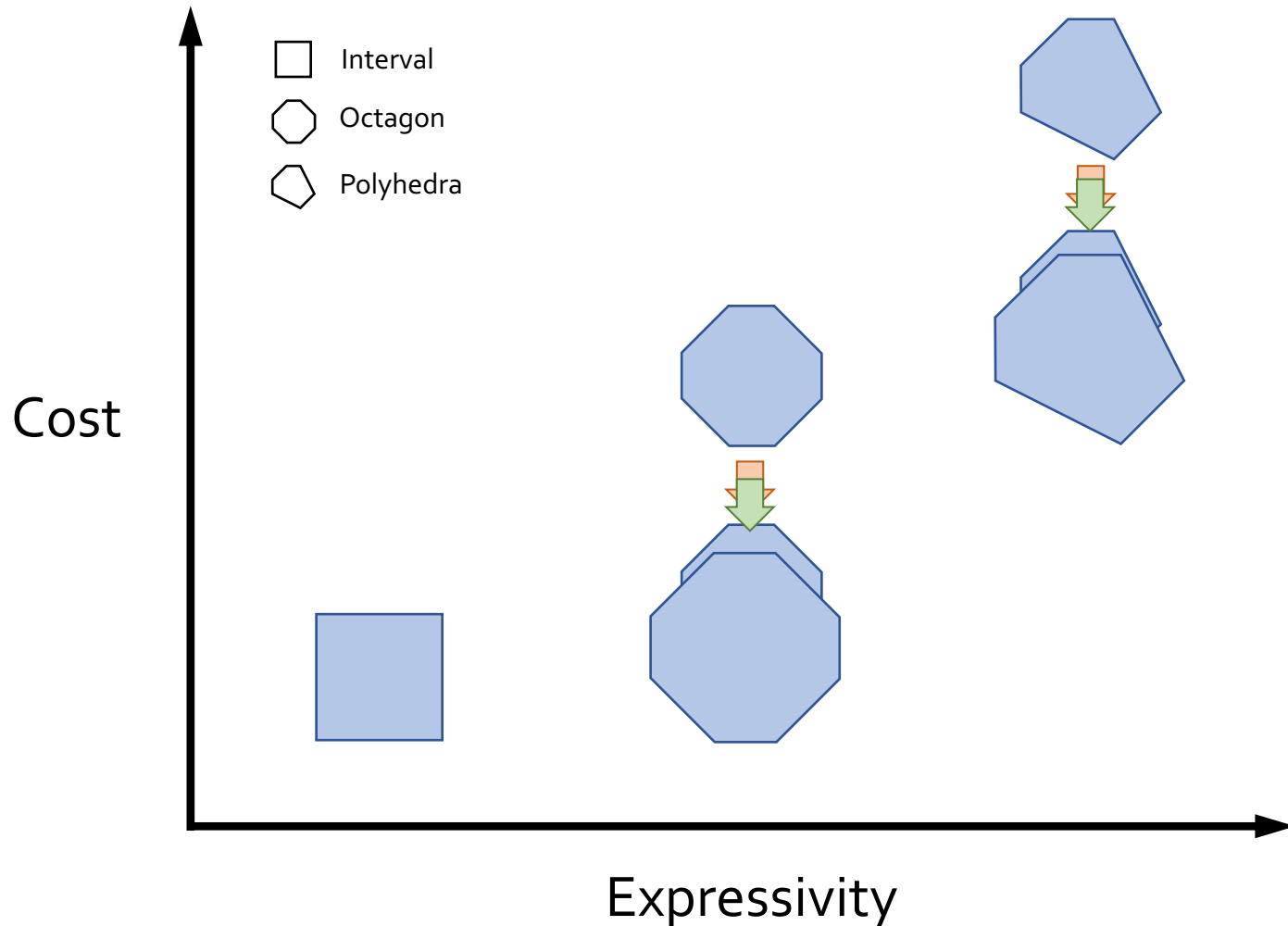


Invariants

$\sqcup$   $\sqcap$   $\sqsubseteq$   $\nabla$   
[x := e] [x < e]

Abstract transformers

# Tradeoff for numerical analysis



Online decomposition  
[PLDI 2015, POPL 2017, POPL 2018]

Drawback: redundant computation during inference of invariants

Learning-based

[OOPSLA 2015] [SAS 2016]  
[CAV 2018]

Drawback: domain-specific, can incur large precision losses

# Tradeoff for numerical analysis

- Interval
- Octagon
- ⬡ Polyhedra

➔ Online decomposition  
[PLDI 2015, POPL 2017, POPL 2018]

**Wanted:** a **generic** method lowering analysis cost **significantly** with **minimal** precision loss

Cost

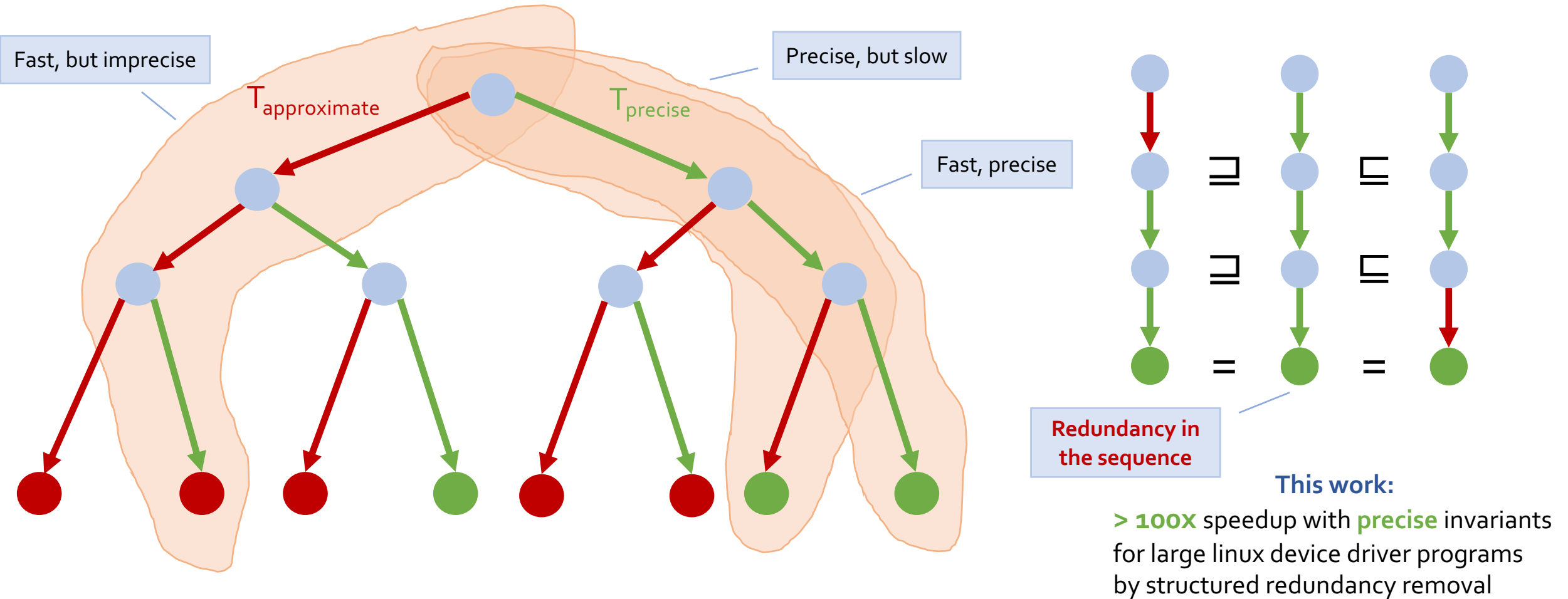
**Key idea:** remove **redundant** computation from analysis **sequences**

➔ Learning-based  
□ [OOPSLA 2015]   ○ [SAS 2016]  
⬡ [CAV 2018]

Drawback: domain-specific,  
can incur large precision losses

Expressivity

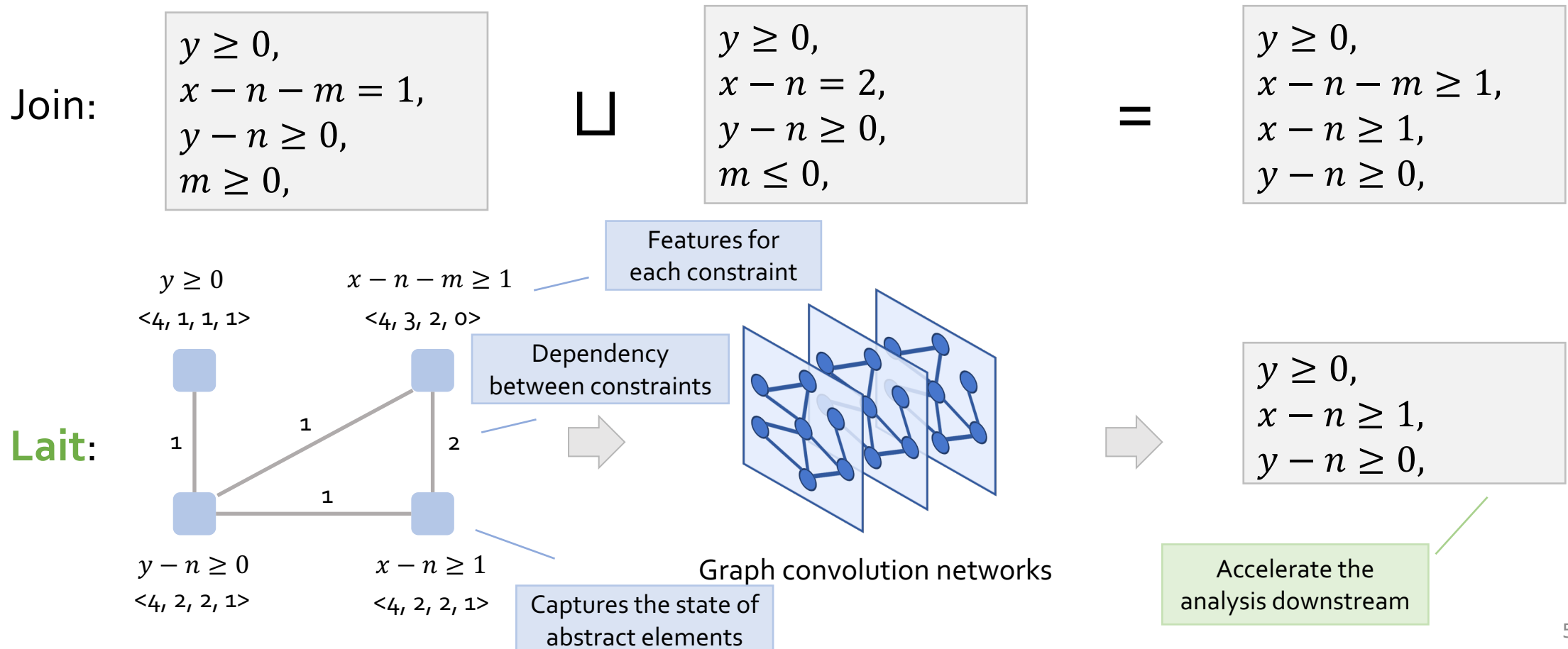
# Key observation: redundancy in analysis sequences



**Challenge:** define and apply approximate transformers for redundancy removal

# Lait: approximate join transformer

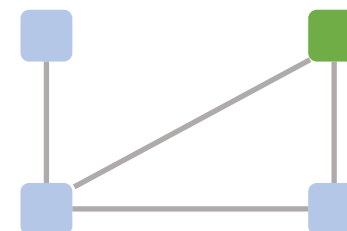
**Lait:** learning-based constraint removal from the expensive join transformer



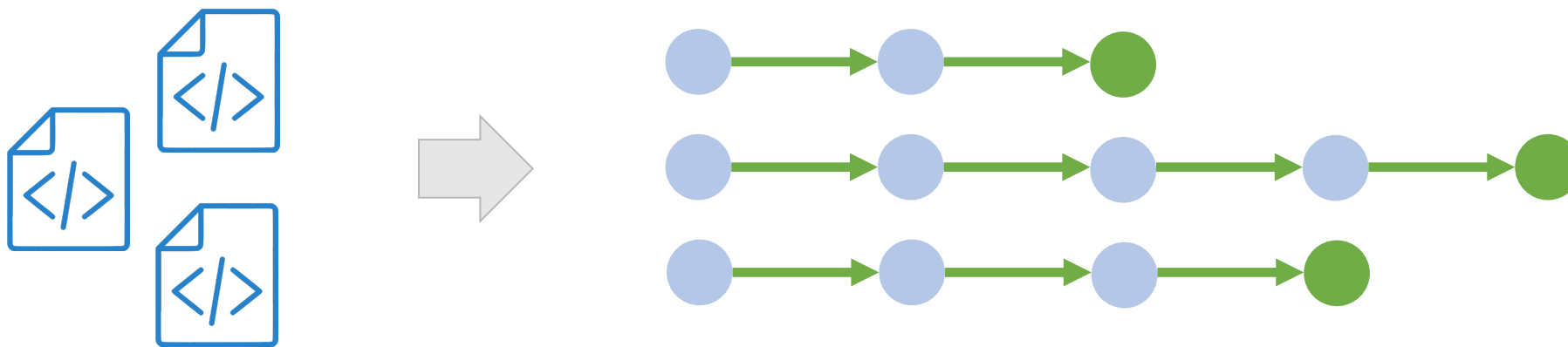
# Our learning algorithm

To train , we need a **supervised** dataset of graphs where removed constraints are labelled:

- **True**, removing the constraint does not affect the analysis precision, or
- **False**, removing the constraint loses precision.

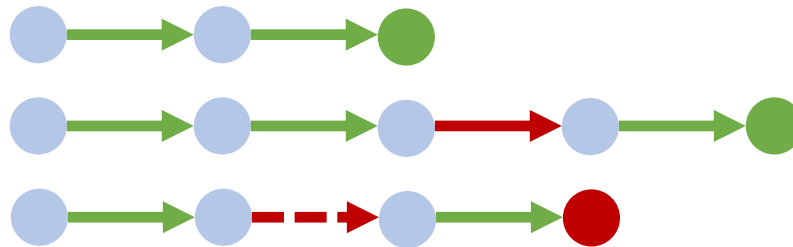
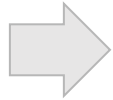
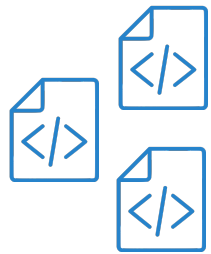


**Step 1:** running precise analysis on training programs to obtain **ground truth** for precision



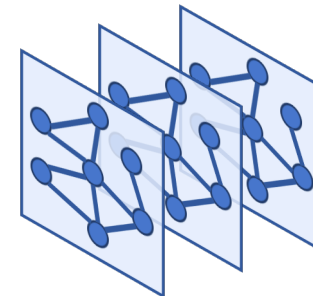
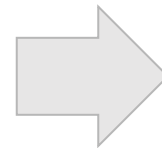
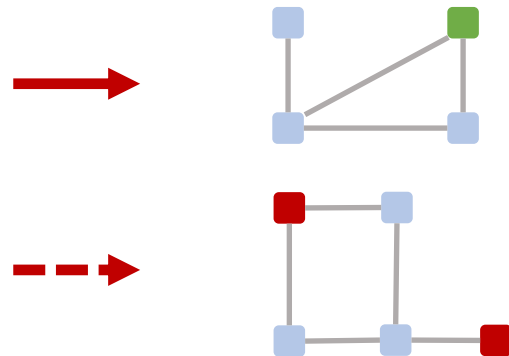
# Our learning algorithm

**Step 2:** running approximate analysis with constraint removal on training programs



$\epsilon$ -greedy : calls Lait with  $1 - \epsilon$  probability, or a random removal policy with  $\epsilon$  probability.

**Step 3:** collect the labelled dataset and train the networks.





# Our learning algorithm

Step 2: running approximate analysis with constraint removal on training programs

**Iterative training:** running steps 2 and 3 for multiple iterations



# Evaluation setup

Instantiation for online decomposed Polyhedra and Octagon analysis

- Implementation incorporated in <http://elina.ethz.ch/> ELINA

SV-COMP benchmarks and crab-llvm analyzer

Lait v.s.

- ELINA: a state-of-the-art library for numerical domains (**ground truth** for precision)
- Poly-RL: an approximate Polyhedra analysis with reinforcement learning [CAV 2018]
- HC: a hand-created heuristics for redundancy removal

Precision = % of program points with the same invariants as ELINA

# Results for Polyhedra analysis

Training on 30 programs

Time limit: 2h, Memory limit: 50GB

Benchmark	Number of program points	ELINA	HC		Poly-RL		Lait	
		time (s)	speedup	precision	speedup	precision	speedup	precision
qlogic_qlge	5748	3474	49x	99	4.2x	98.8	53x	100
peak_usb	1300	1919	325x	81	1.3x	95.1	315x	100
stvogox	7726	3401	4.6x	95	MO	100	6.3x	97
acenic	1359	3290	TO	65	1.1x	100	223x	100
qla3xxx	2141	2085	163x	95	210x	99.8	169x	100
cx25840	1843	56	8.8x	83	0.7x	97.9	9.9x	83
mlx4_en	6504	46	1.2x	91	1.2x	98.9	1.0x	100
advansys	3568	109	1.7x	92	crash	98.8	1.4x	99.7
i7300_edac	309	36	2.6x	83	1.2x	99.8	1.4x	99
oss_sound	2465	2428	245x	80	1.2x	100	229x	80

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# Statistics on the number of constraints

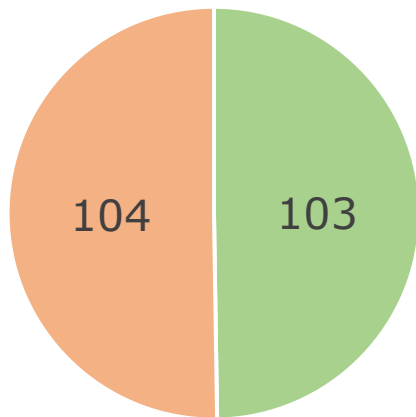
$m$ : the number of constraints in abstract elements

Benchmark	$m_{ELINA}$		$m_{HC}$		$m_{Poly-RL}$		$m_{Lait}$	
	max	avg	max	avg	max	avg	max	avg
qlogic_qlge	267	6	19	4	205	5	33	4
peak_usb	48	7	17	5	48	7	24	7
stvogox	74	12	32	14	-	-	35	13
acenic	98	9	-	-	98	8	28	5
qla3xxx	284	17	30	9	218	15	19	8
cx25840	26	10	17	7	26	9	17	8
mlx4_en	56	4	53	4	54	4	56	4
advansys	38	9	37	9	-	-	38	8
i7300_edac	41	14	20	9	41	14	28	11
oss_sound	47	9	38	7	47	8	23	7

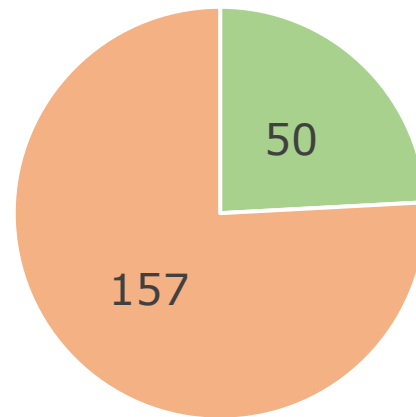
# Results for Polyhedra analysis

On 207 programs for which ELINA does not finish within 2h:

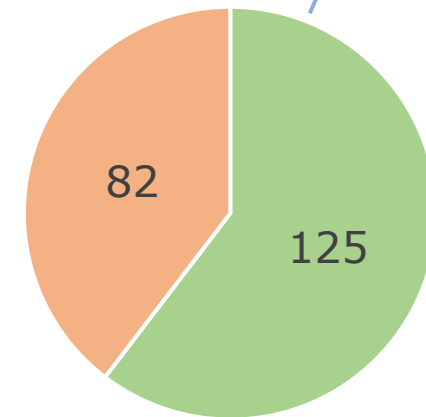
not finished  
finished



HC



Poly-RL



Lait

Faster than HC  
and Poly-RL

# Results for Octagon analysis

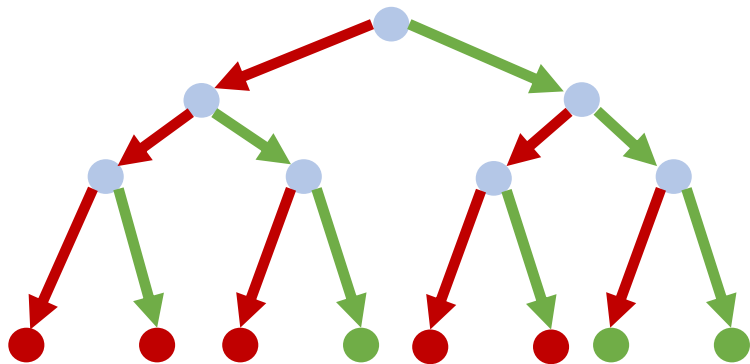
Training on 10 programs

Time limit: 2h, Memory limit: 50GB

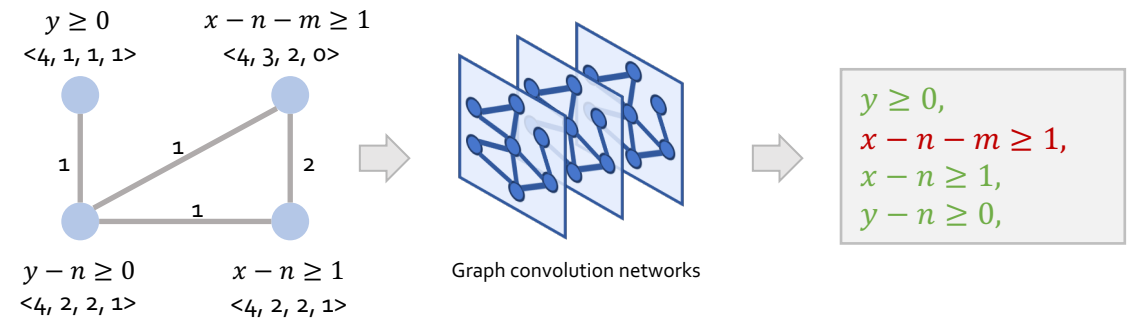
Benchmark	Number of program points	ELINA	HC		Lait	
		time (s)	speedup	precision	speedup	precision
advansys	3408	34	1.22x	99.4	1.15x	98.8
net_unix	2037	13	TO	52.5	1.45x	95.1
vmwgfx	7065	45	1.08x	100	1.24x	100
phoenix	644	26	1.55x	96.9	1.31x	100
mwl8k	4206	27	1.05x	64.2	1.55x	99.8
saa7164	6565	117	1.00x	57.8	1.54x	97.9
md_mod	8222	1309	TO	68.1	28x	98.9
block_rsxx	2426	14	1.11x	73.9	1.26x	98.8
ath_ath9k	3771	26	1.07x	65.7	1.33x	99.8
synclik_gt	2324	44	1.28x	100	1.23x	100

# Summary

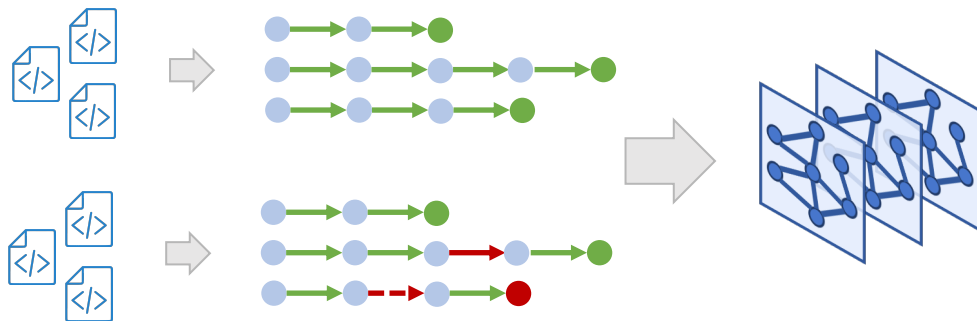
## Redundancy in numerical analysis



## Approximate join by constraint removal



## Iterative learning algorithm



## Promising results on two domains

Benchmark	Number of program points	ELINA	HC		Poly-RL		Lait	
		time (s)	speedup	precision	speedup	precision	speedup	precision
qlogic_qlge	5748	3474	49x	99	4.2x	98.8	53x	100
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